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CONTUR-A FORTRAN IV SUBROUTINE FOR THE
PLOTING OF CONTOUR LINES

George W. Hartwig, Jr.

Ballistic Research Laboratories

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March 1973

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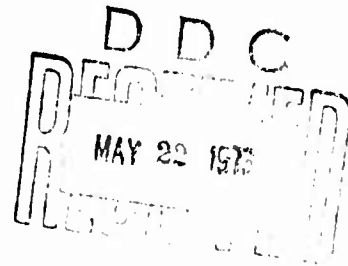
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MEMORANDUM REPORT NO. 2282

CONTUR-A FORTRAN IV SUBROUTINE FOR
THE PLOTTING OF CONTOUR LINES.

by

George W. Hartwig, Jr.



March 1973

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George W. Hartwig, Jr.

Applied Mathematics Laboratory

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In performing engineering or scientific data analysis or computations it frequently becomes necessary to examine data which is a single valued function of two independent variables. One convenient method of displaying this type of data is with contour plots. This report describes an efficient algorithm for construction of contour lines and the implementation of this algorithm as a FORTRAN IV subroutine, CONTUR.

TABLE OF CONTENTS

	Page
ABSTRACT	3
LIST OF ILLUSTRATIONS.	7
I. INTRODUCTION	9
II. THE ALGORITHM.	9
III. THE SUBROUTINE	13
IV. CONTUR INPUT VARIABLES	14
V. PLTCCD INPUT VARIABLES	15
APPENDICES	17
A. Examples of CONTUR Output.	17
B. Flow Chart of Subroutine CONTUR	25
C. Listing of Subroutine CONTUR.	29
DISTRIBUTION LIST.	33

LIST OF ILLUSTRATIONS

Figure	Page
1. A Typical Cell.	10
2. The Interpolation Scheme.	11
3. Error Condition. 2	12
4. Error Condition 3	13
A-1. 3-D Plot of $Z = \sin(x + y)/(1 + (x - y)^2)$	18
A-2. Contours of $Z = \sin(x + y)/(1 + (x - y)^2)$	19
A-3. 3-D Plot of Experimental Data	20
A-4. Contours of Experimental Data	21
A-5. 3-D Plot of $Z = \sin(\sqrt{x^2 + y^2})/\sqrt{x^2 + y^2} $	22
A-6. Dense Grid Contours of $Z = \sin(\sqrt{x^2 + y^2})/\sqrt{x^2 + y^2} $	23
A-7. Course Grid Contours of $Z = \sin(\sqrt{x^2 + y^2})/\sqrt{x^2 + y^2} $	24

I. INTRODUCTION

In performing engineering or scientific data analysis it frequently becomes necessary to examine data which is a single valued function of two independent variables. A common and useful technique for displaying such data is through the use of contour plots. When three independent variables are involved any method of graphic display is cumbersome, but the plotting of contours in two dimensions for several values of the third independent variable may be the most practical alternative.

Organizations heavily involved in scientific computation utilizing digital computers frequently need to reduce results into an easily comprehensible form such as contour plots. Accordingly, it is highly desirable that an easy to use subroutine for contour plotting be available for the organization's computer users. CONTUR is such a subroutine, written in FORTRAN IV, and hence, is compatible with many digital computers in use today. The subroutine described herein was designed to work in conjunction with the California Computer Products, model 780 digital, incremental plotting system and the associated plotting subroutines in use at BRL. However, with simple modifications, CONTUR may be used with other forms of graphic display equipment.

II. ALGORITHM

The data for which contours are to be drawn is assumed to be a discrete tabulation of the single valued function

$$Z = f(x,y) \quad (1)$$

for x,y , in the range over which contours are desired. For a fixed Z , $Z=Z_0$, Eq. (1) may be written

$$Y = g(x,z_0). \quad (2)$$

In this form the curve is called a contour and in general a different contour would occur for each value of Z_0 . Usually the function, $f(x,y)$ is not known, the data arising either from experiment or by numerical approximation techniques. Hence, the explicit expression as a function of x and Z_0 , Eq. (2), is not available and a numerical procedure for determining the contours is necessary.

The algorithm described below represents a significant simplification of the algorithm described by James Downing [1].

The algorithm is derived by focusing attention on four adjacent data points $Z_{i,j}$, $Z_{i+1,j}$, $Z_{i,j+1}$ and $Z_{i+1,j+1}$ where the corresponding independent variables have the values (X_i, Y_j) , (X_{i+1}, Y_j) etc. Assuming the data contains I points in the x direction and J points in the Y direction, the algorithm must be applied to $N = (I-1)(J-1)$ cells.

Within such a cell, Figure 1, the center point is located and assigned a Z value equal to the average of the four Z values at the corners. These five points are then connected with line segments which are in turn numbered one through eight in a clockwise direction.

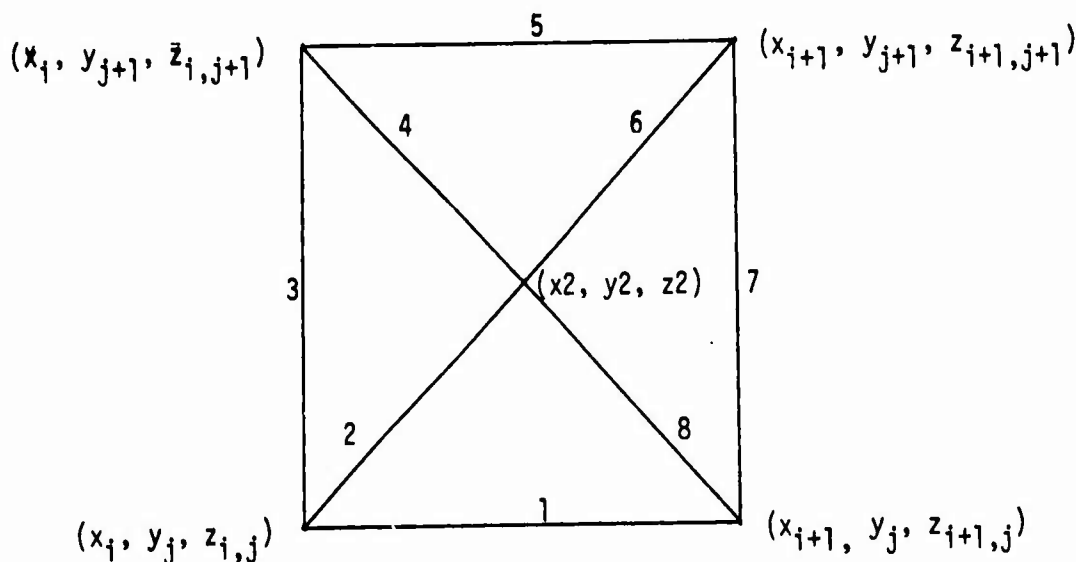


Figure 1. A Typical Cell.

Each segment is then tested to see if the required contour intersects with it, in the following manner. Starting with segment one, the contour value Z_0 is subtracted from the end points.

$$\begin{aligned} T_1 &= Z_{i,j} - Z_0 \\ T_2 &= Z_{i+1,j} - Z_0 \end{aligned} \quad (3)$$

If the quantity

$$\Delta = T_1 \cdot T_2 \quad (4)$$

is greater than zero, the entire segment is either above or below Z_0 , if Δ equals zero, either $Z_{i,j}$ or $Z_{i+1,j}$ is equal to Z_0 , and if Δ is less than zero the contour intersects the segment. In this last case the point of intersection, x_0 is found by linear interpolation (see Figure 2) with x_0 given by

$$x_0 = (Z_0 - Z_{i,j})(x_{i+1} - x_i) / (Z_{i+1,j} - Z_{i,j}) + x_i. \quad (5)$$

The x and y values of this intersection are then stored in temporary arrays PX and PY.

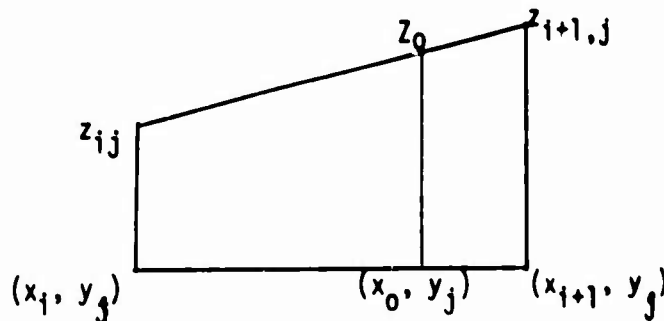


Figure 2. The Interpolation Scheme.

The procedure is then repeated for segments two through eight. When segment eight is completed, the points stored in PX and PY are plotted and the next set of points are considered.

Before the ordered pairs (PX, PY) can be plotted successfully there are several conditions which must be tested for and if present, properly handled. (1) If all four of the cell's corner points are equal to Z_0 , no points should be plotted. (2) When the contour intersects segment eight, the PX and PY arrays must be reordered. The reason for this becomes obvious when one remembers that the segments are tested in a clockwise direction. For instance, assume CONTUR finds intersections on segments one, seven and eight. Plotting these points as originally stored would result in an extraneous line being drawn. See Figure 3. By simply rearranging the points so that they are stored seven, eight, one, the correct contour is drawn.

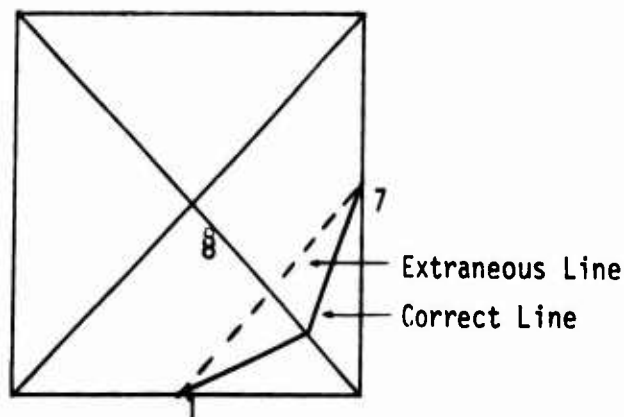


Figure 3. Error Condition 2.

(3) Provision is also made for the case where two contours of the same value pass through the cell. This occurs only when two opposite Z values are greater than Z_0 and the other two points are less than Z_0 . By noting if the center point, Z_2 , is greater than or less than Z_0 , the paths taken by the contours are specifically known and are plotted as a special case. See Figure 4.

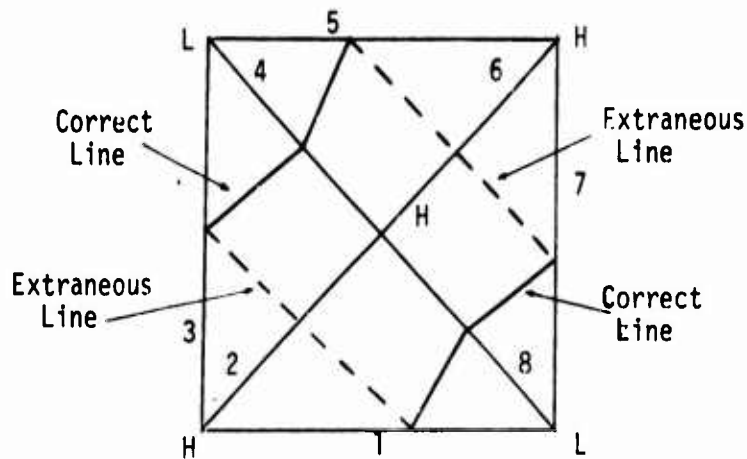


Figure 4. Error Condition 3.

III. THE SUBROUTINE

CONTUR is accessed through the statement

CALL CONTUR (Z,X,Y,IS,IY,DZ,NZ,IZ).

Z,X,Y are the arrays containing the values Z_{ij} , X_i and Y_j , respectively. IX and IY are the number of points in the X dimension and Y dimension. The subroutine requires that Z be of dimensions (IZ,IY). DZ(NZ) is a one dimensional array containing the Z values at which contours are desired. NZ is the number of these values. The declared number of rows in the Z array is IZ.

Since the subroutine uses just four data points at a time, requiring no knowledge of where it has been or where it is going, enormous amounts of data can be handled by reloading the Z array and calling CONTUR several times with different portions of the data.

The computer time required by CONTUR depends on the size of the Z array, the number of values at which contours are desired and the smoothness or irregularity of the data, with time increasing for large arrays, large numbers of contour values and irregular data. For some typical times see the examples of contour output.

In order to keep the subroutine as efficient and machine independent as possible, no labeling of contours is done, nor are any borders or titles plotted in CONTUR. The user must initialize the plot routines and set scales prior to calling CONTUR. PLTCCD is a predefined subroutine on the Ballistic Research Laboratories BRLESC computers that generates input data for the Cal Comp 780 digital, incremental plotting system, and must be replaced for use of CONTUR on other computer systems.

BRLESC users should note that the positioning on the plotter page and scales used by CONTUR are determined by the latest reference to PLTCCS. [1] Thus, it may be necessary to reset the plotting scales before calling CONTUR.

IV. CONTUR INPUT VARIABLES

- Z(IZ,IY) - is a two dimensional array containing the functional values of the data.
- X(IX) - is a one dimensional array containing the values of one of the independent variables.
- Y(IY) - is a one dimensional array containing the values of the other independent variable.
- IX - is the number of elements in the X array.
- IY - is the number of elements in the Y array.
- DZ(NZ) - is a one dimensional array containing the Z values at which contours are desired.
- NZ - is the number of elements in the NZ array.
- IZ - is the number of declared rows in the Z array.

V. PLTCCD INPUT VARIABLES

- N=1,L=0 - signifies that a line plot is to be drawn.
- PX(I),PY(J)- are arrays containing the X and Y coordinates to be plotted. The First point plotted is Px(I),PY(J).
- K - is the number of data pairs to be plotted
- M=0 - causes the subroutine to start a new curve with the point (PX(I), PY(J)).
- M=1 - causes the subroutine to continue the curve plotted by the previous PLTCCD entry.

REFERENCES

1. Downing, James A., "The Automatic Construction of Contour Plots with Applications to Numerical Analysis Research," The University of Texas Computation Center, Austin, Texas, January 1966.
2. Coleman, Monte W., Lanahan, John V., "BRLESC FORTRAN Plotting Subroutines," ARDC Technical Report No. 6. July 1970.
3. Nagy, Nicholas J. (III), "The Graphical Representation of Two Variable Data", Los Alamos Scientific Laboratory, Report No. LA-4796, November 1971.
4. Lintner, M. A., "Proj-Algorithm and Computer Programs for the Hidden Line Problem for Single Valued Surfaces", Idaho Nuclear Corporation, December 1969.

APPENDIX A

Examples of CONTUR Output

Figure A-1 is a three dimensional graph of the function

$$Z = \text{SIN} (x + y)/(1 + (x - y)^2) \quad \text{A-1}$$

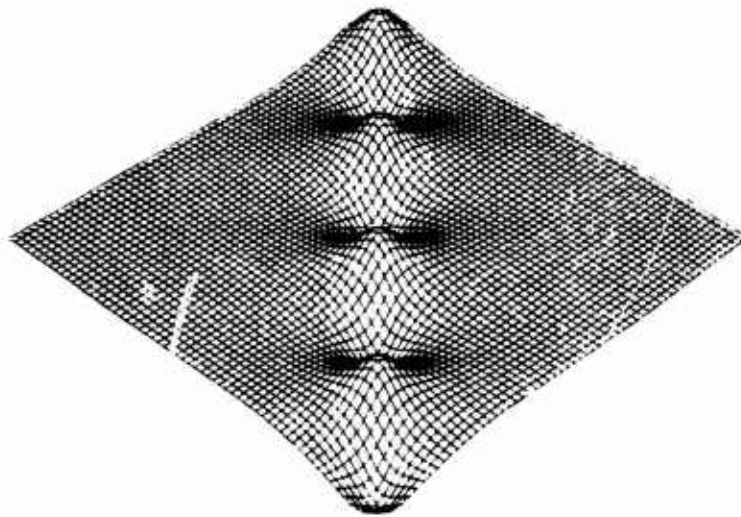
as plotted by the subroutine GRAF3D(3). Although this plot is interesting and demonstrates general trends, it is virtually impossible to retrieve any useful quantitative information from it. Figure A-2 is a contour plot as drawn by CONTUR of the same data. The contour lines are at values of .1, .4, .6, and .9. The Z array contains 3600 points and CONTUR required 14.4 seconds on the BRLESC II computer to generate the curves.

Figures A-3 and A-4 represent experimental data. Again the contour plot is the more analytically useful, although not as esthetically pleasing as the 3-D plot. The PRO1 subroutine (4) was used in this case to generate the three dimensional plot.

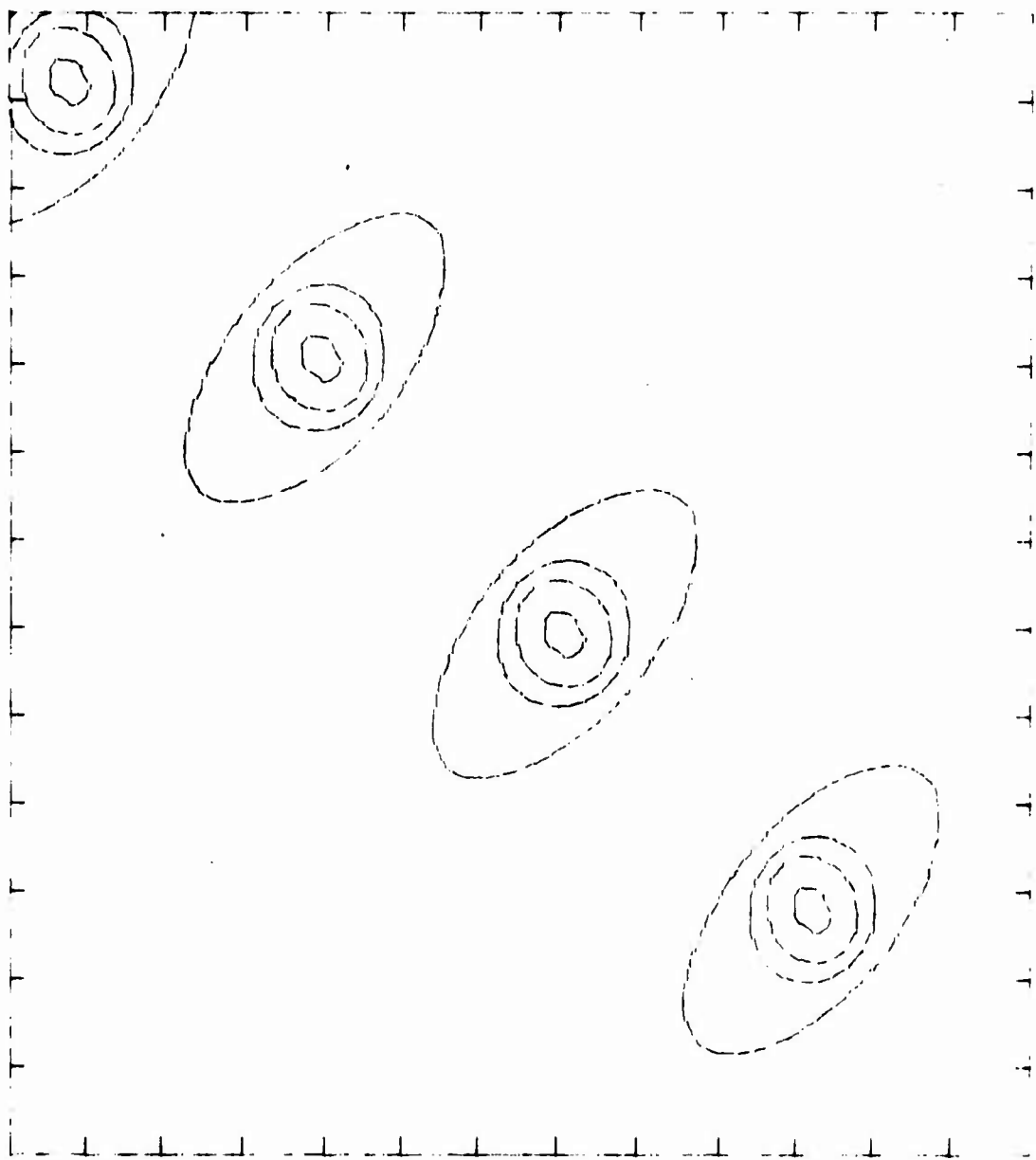
Figures A-5,6,7 are included to demonstrate the results of allowing the data gride to become too goarse. Figure A-5 is the 3-D representation of

$$Z = |\text{SIN} (\sqrt{x^2 + y^2})/(\sqrt{x^2 + y^2})| \quad -20 \leq x, y \leq 20.$$

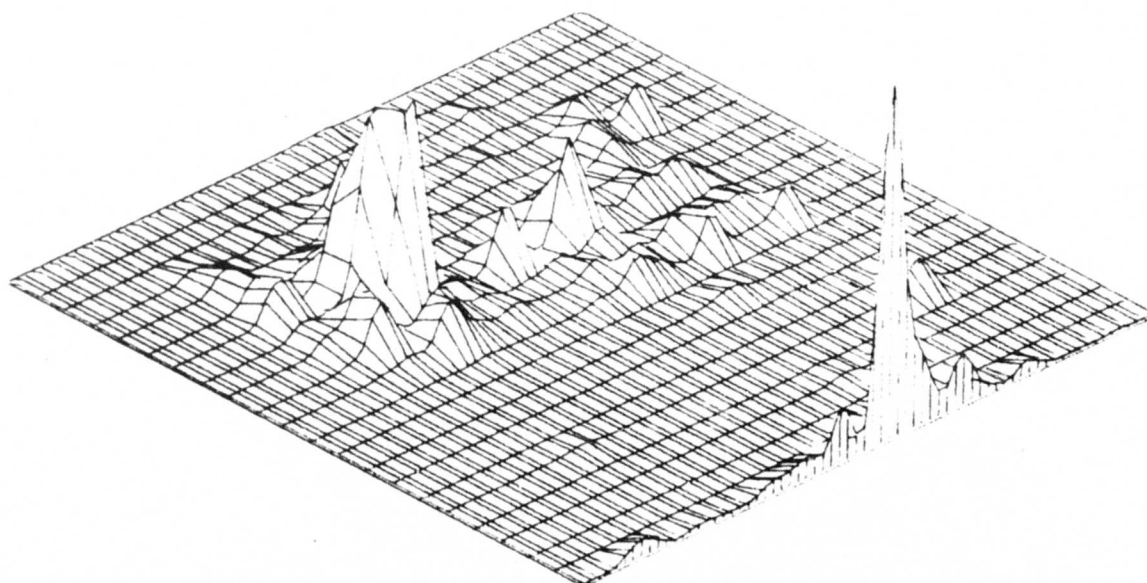
Both Figures A-6 and A-7 are contour plots of the above function with contour lines drawn at Z values of .1, .4, .6, and .9. In Figure A-6 the grid contains 10000 points and the representation is accurate. The grid in Figure A-7 contains only 2500 points and the interpolation scheme is no longer sufficiently accurate to portray the function correctly. The BRLESC I computer required 60.6 seconds to generate A-6 and 19.2 seconds for A-7.



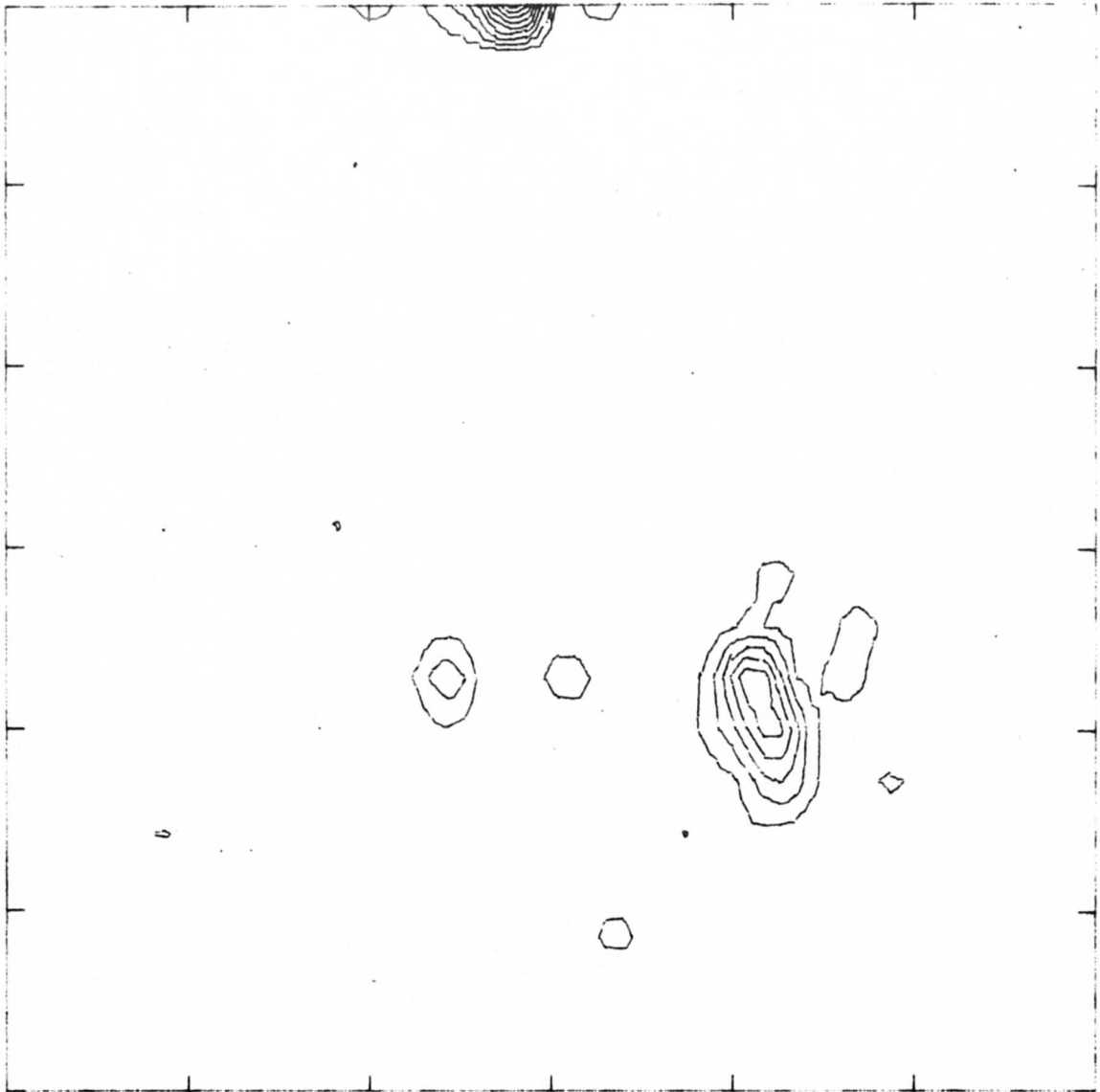
A-1. 3-D Plot of $z = \sin(x + y) / (1 + (x - y)^2)$



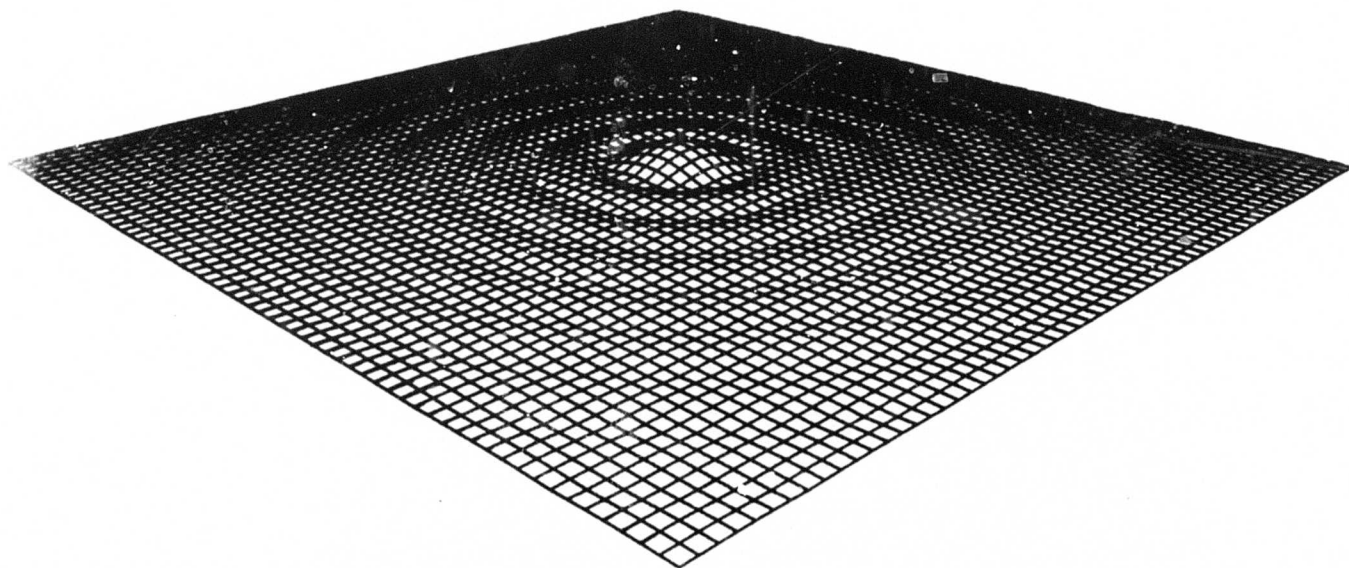
A-2. Contours of $Z = \sin(x - y)/(1 + (x - y)^2)$



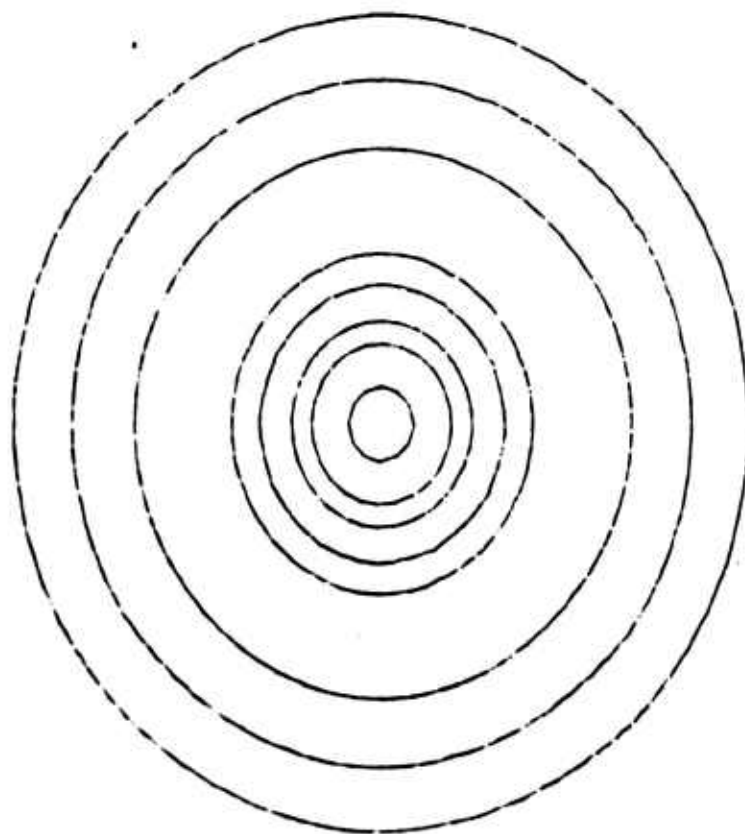
A-3. 3-D Plot of Experimental Data



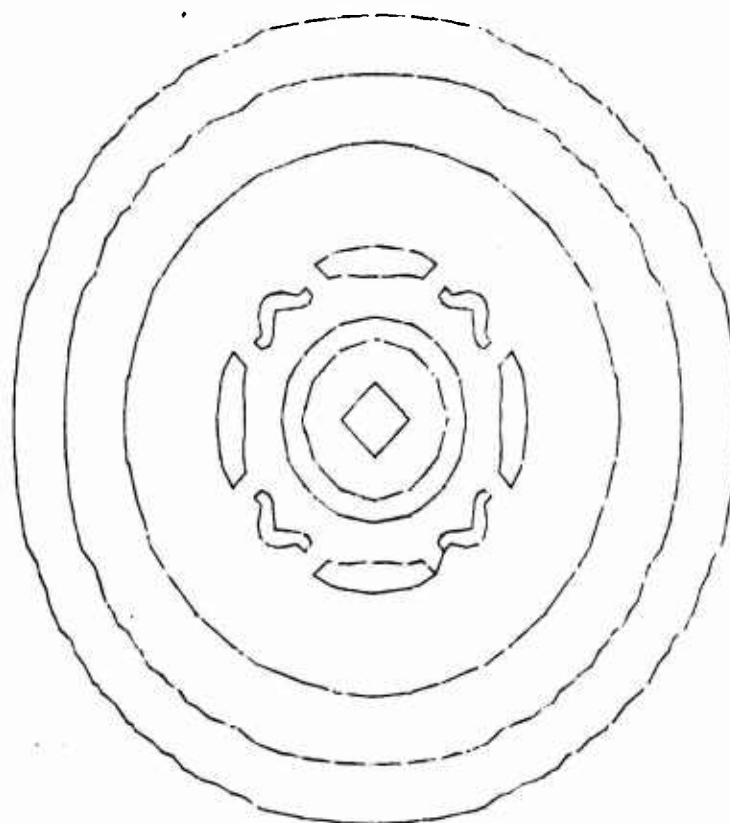
A-4. Contours of Experimental Data



A-5. 3-D Plot of $Z = \left| \frac{\sin(\sqrt{x^2 + y^2})}{\sqrt{x^2 + y^2}} \right|$



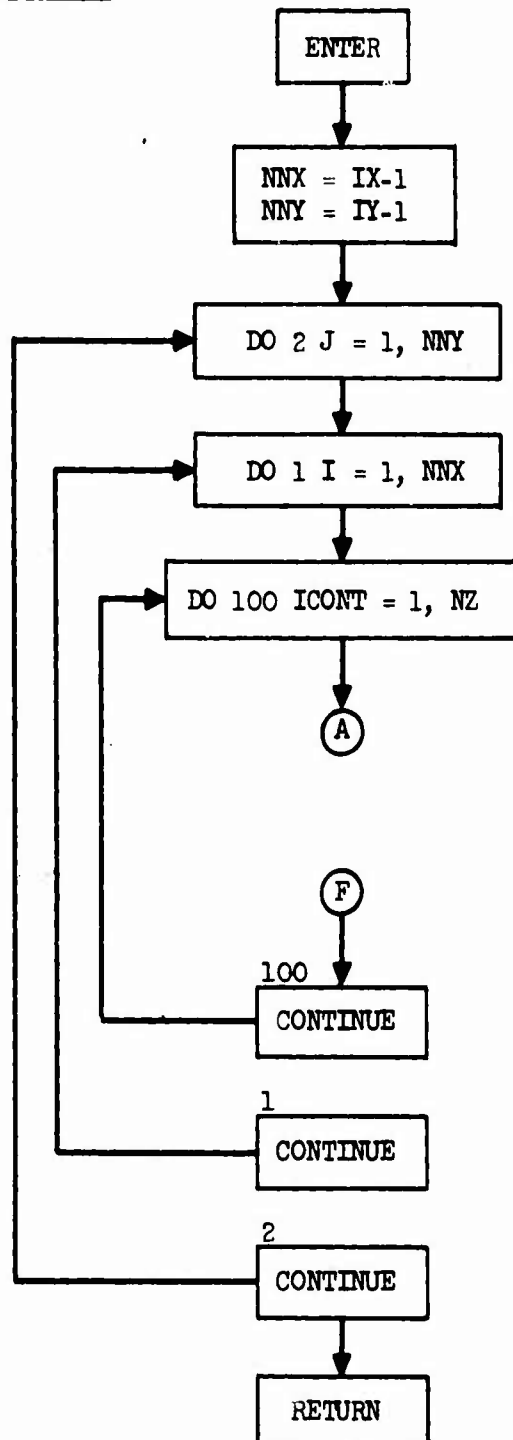
A-6. Dense Grid Contours of $Z = |8 \sin(\sqrt{x^2 + y^2}) / \sqrt{x^2 + y^2}|$

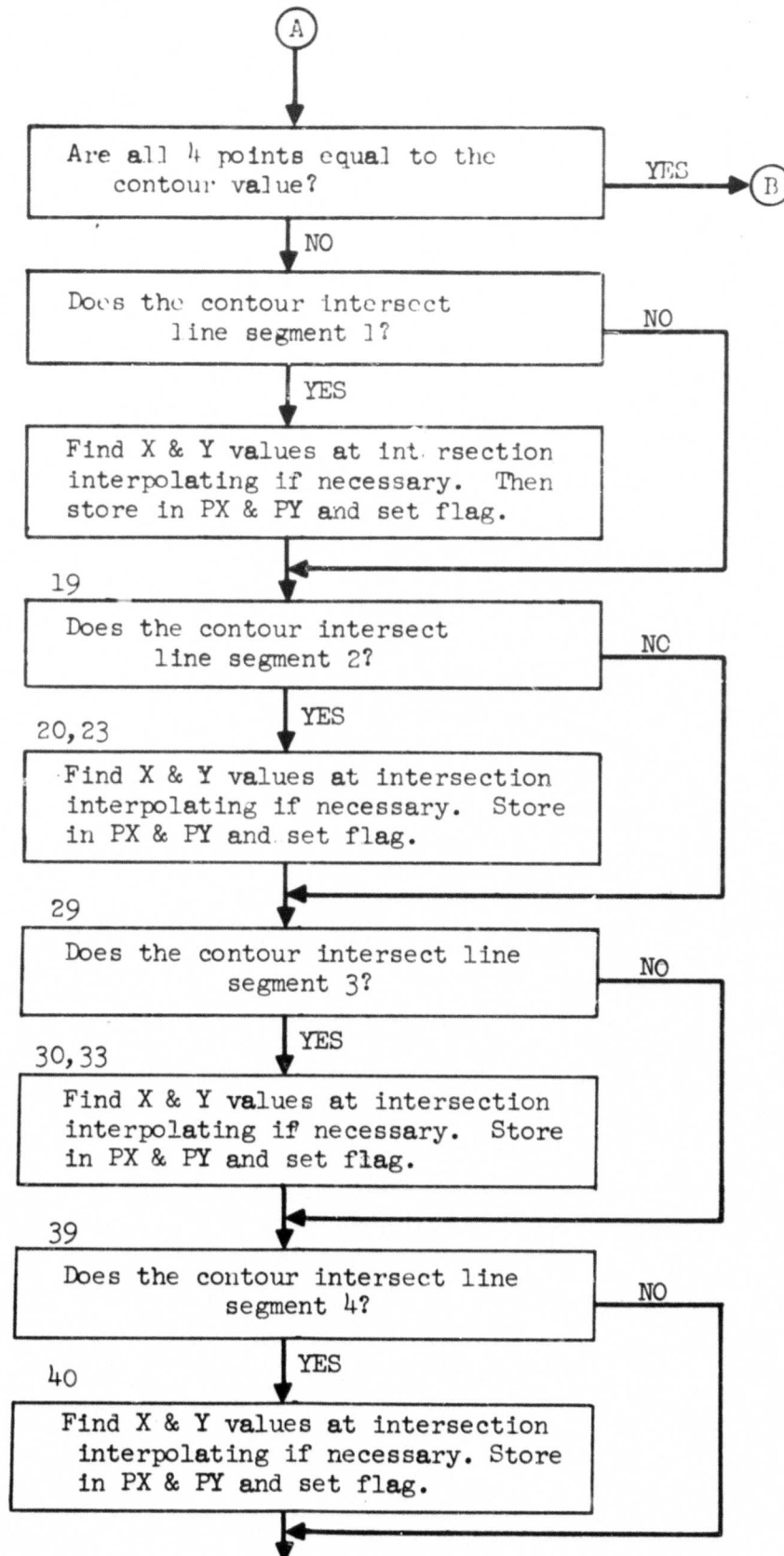


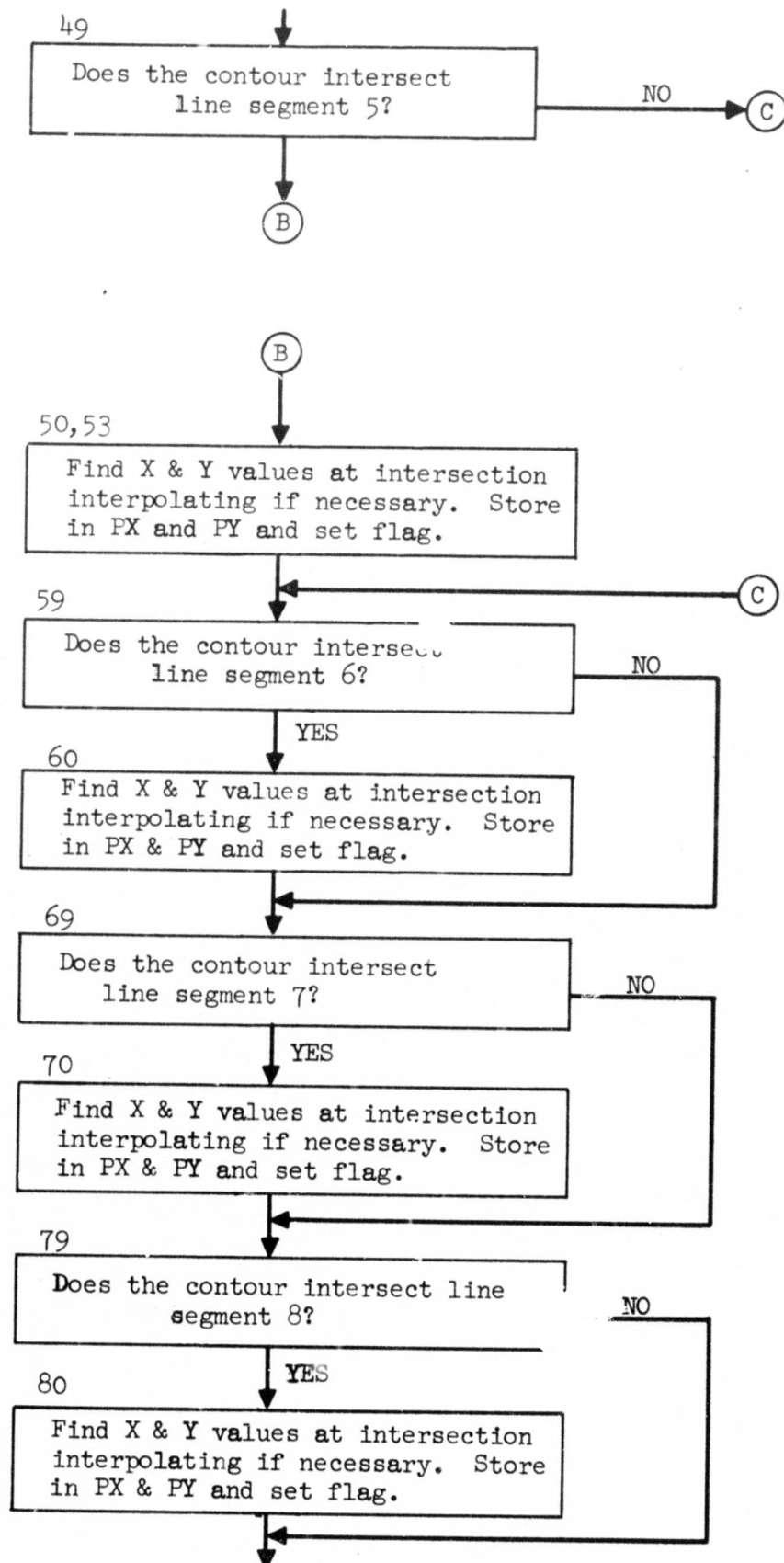
A-7. Coarse Grid Contours of $Z = |\sin(\sqrt{x^2 + y^2})|/\sqrt{x^2 + y^2}$

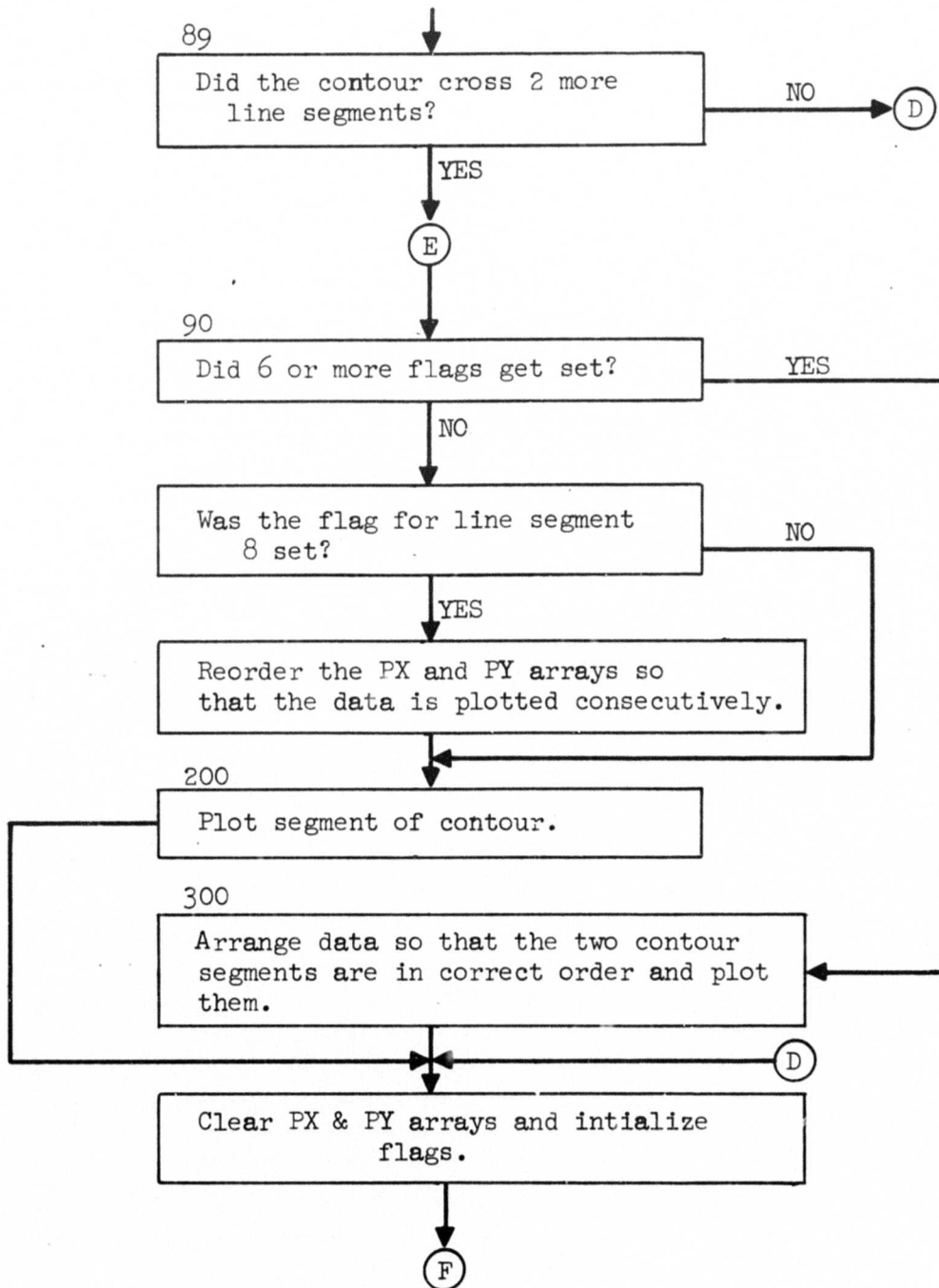
APPENDIX B

Flow Chart of Contur









C	SUBROUTINE CONTUR (Z, X, Y, IX, IY, DZ, NZ, IZ)	CONTR 1
C	DIMENSION X(IX),Y(IY),Z(IZ,IY),PX(8),PY(8),KCHK(8),DZ(NZ)	CONTR 2
C		CONTR 3
C	THIS SUBROUTINE PLOTS NZ CONTOURS AT DZ VALUES.	CONTR 4
C		CONTR 5
C	X AND Y ARE ONE DIMENSIONAL ARRAYS OF LENGTH IX AND IY, RESPECTIVELY.	CONTR 6
C		CONTR 7
C	Z IS A TWO DIMENSIONAL ARRAY OF SIZE (IX,IY).	CONTR 8
C		CONTR 9
C	DZ IS A ONE DIMENSIONAL ARRAY OF LENGTH NZ IN WHICH THE Z VALUES AT	CONTR 10
C	WHICH CONTOURS ARE DESIRED ARE PLACED.	CONTR 11
C		CONTR 12
C	THIS VERSION OF CONTUR WAS COMPLETED IN FEBRUARY 1973.	CONTR 13
C		CONTR 14
C	IC=0	CONTR 15
C	NNX=IX-1	CONTR 16
C	NNY=IY-1	CONTR 17
C	DO 2 J=1,NNY	CONTR 18
C	DO 1 I=1,NNX	CONTR 19
C	DO 100 ICONT=1,NZ	CONTR 20
C	Z0=DZ(ICONT)	CONTR 21
C		CONTR 22
C	IF ALL FOUR DATA POINTS ARE EQUAL TO Z0, DO NOT PLOT ANY LINES FOR	CONTR 23
C	THIS CELL.	CONTR 24
C		CONTR 25
C	IF(Z(I,J).EQ.Z0.AND.Z(I+1,J).EQ.Z0.AND.Z(I,J+1).EQ.Z0.AND.	CONTR 26
C	IZ(I+1,J+1).EQ.Z0) GOTO 100	CONTR 27
C		CONTR 28
C	TEST SEGMENT 1 FOR AN INTERSECTION WITH THE CONTOUR LINE.	CONTR 29
C		CONTR 30
C	T1=Z(I,J)-Z0	CONTR 31
C	T2=Z(I+1,J)-Z0	CONTR 32
C	D=T1*T2	CONTR 33
C	IF(D)10,11,19	CONTR 34
C	10 IC=IC+1	CONTR 35
C	PX(IC)=-T1*(X(I+1)-X(I))/(Z(I+1,J)-Z(I,J))+X(I)	CONTR 36
C	PY(IC)=Y(J)	CONTR 37
C	KCHK(1)=1	CONTR 38
C	GOTO 19	CONTR 39
C	11 IF(T1.NE.0.0) GOTO 13	CONTR 40
C	IC=IC+1	CONTR 41
C	PX(IC)=X(I)	CONTR 42
C	PY(IC)=Y(J)	CONTR 43
C	KCHK(1)=1	CONTR 44
C	IF(T2)19,13,19	CONTR 45
C	13 IC=IC+1	CONTR 46
C	PX(IC)=X(I+1)	CONTR 47
C	PY(IC)=Y(J)	CONTR 48
C	KCHK(1)=1	CONTR 49
C		CONTR 50
C	TEST SEGMENT 2 FOR AN INTERSECTION WITH THE CONTOUR LINE.	CONTR 51
C		CONTR 52
C	19 T3=.25*(Z(I,J)+Z(I+1,J)+Z(I,J+1)+Z(I+1,J+1))-Z0.	CONTR 53
C	D=T1*T3	CONTR 54
C	X2=(X(I+1)+X(I))* .5	CONTR 55
C	Y2=(Y(J+1)+Y(J))* .5	CONTR 56
C	Z2=T3+Z0	CONTR 57
C	IF(D)20,23,29	CONTR 58
C	20 IC=IC+1	CONTR 59
C		CONTR 60

PX(IC)=-T1*(X2-X(I))/(Z2-Z(I,J))+X(I)	CONTR 61
PY(IC)=-T1*(Y2-Y(J))/(Z2-Z(I,J))+Y(J)	CONTR 62
KCHK(2)=1	CONTR 63
GOTO 29	CONTR 64
23 IF(T3.NE.0.0) GOTO 29	CONTR 65
IC=IC+1	CONTR 66
PX(IC)=X2	CONTR 67
PY(IC)=Y2	CONTR 68
KCHK(2)=1	CONTR 69
C	CONTR 70
C TEST SEGMENT 3 FOR AN INTERSECTION WITH THE CONTOUR LINE.	CONTR 71
C	CONTR 72
29 T2=Z(I,J+1)-Z0	CONTR 73
D=T1*T2	CONTR 74
IF(D)30,33,39	CONTR 75
30 IC=IC+1	CONTR 76
PX(IC)=X(I)	CONTR 77
PY(IC)=-T1*(Y(J+1)-Y(J))/(Z(I,J+1)-Z(I,J))+Y(J)	CONTR 78
KCHK(3)=1	CONTR 79
GOTO 39	CONTR 80
33 IF(T2.NE.0.0) GOTO 39	CONTR 81
IC=IC+1	CONTR 82
PX(IC)=X(I)	CONTR 83
PY(IC)=Y(J+1)	CONTR 84
KCHK(3)=1	CONTR 85
C	CONTR 86
C TEST SEGMENT 4 FOR AN INTERSECTION WITH THE CONTOUR LINE.	CONTR 87
C	CONTR 88
39 T1=Z(I,J+1)-Z0	CONTR 89
D=T1*T3	CONTR 90
IF(D)40,49,49	CONTR 91
40 IC=IC+1	CONTR 92
PX(IC)=-T1*(X2-X(I))/(Z2-Z(I,J+1))+X(I)	CONTR 93
PY(IC)=-T1*(Y2-Y(J+1))/(Z2-Z(I,J+1))+Y(J+1)	CONTR 94
KCHK(4)=1	CONTR 95
C	CONTR 96
C TEST SEGMENT 5	CONTR 97
C	CONTR 98
49 T2=Z(I+1,J+1)-Z0	CONTR 99
D=T1*T2	CONTR100
IF(D)50,53,59	CONTR101
50 IC=IC+1	CONTR102
PX(IC)=-T1*(X(I+1)-X(I))/(Z(I+1,J+1)-Z(I,J+1))+X(I)	CONTR103
PY(IC)=Y(J+1)	CONTR104
KCHK(5)=1	CONTR105
GOTO 59	CONTR106
53 IF(T2.NE.0.0) GOTO 59	CONTR107
IC=IC+1	CONTR108
PX(IC)=X(I+1)	CONTR109
PY(IC)=Y(J+1)	CONTR110
KCHK(5)=1	CONTR111
C	CONTR112
C TEST SEGMENT 6	CONTR113
C	CONTR114
59 D=T2*T3	CONTR115
IF(D)60,69,69	CONTR116
60 IC=IC+1	CONTR117
PX(IC)=-T2*(X2-X(I+1))/(Z2-Z(I+1,J+1))+X(I+1)	CONTR118
PY(IC)=-T2*(Y2-Y(J+1))/(Z2-Z(I+1,J+1))+Y(J+1)	CONTR119
KCHK(6)=1	CONTR120

C		CONTR121
C	TEST SEGMENT 7	CONTR122
C		CONTR123
	69 T1=T2	CONTR124
	T2=Z(I+1,J)-Z0	CONTR125
	D=T1*T2	CONTR126
	IF(D)70,79,79	CONTR127
	70 IC=IC+1	CONTR128
	PX(IC)=X(I+1)	CONTR129
	PY(IC)=-T1*(Y(J)-Y(J+1))/(Z(I+1,J)-Z(I+1,J+1))+Y(J+1)	CONTR130
	KCHK(7)=1	CONTR131
C		CONTR132
C	TEST SEGMENT 8	CONTR133
C		CONTR134
	79 D=T2*T3	CONTR135
	IF(D)80,89,89	CONTR136
	80 IC=IC+1	CONTR137
	PX(IC)=-T3*(X(I+1)-X2)/(Z(I+1,J)-Z2)+X2	CONTR138
	PY(IC)=-T3*(Y(J)-Y2)/(Z(I+1,J)-Z2)+Y2	CONTR139
	KCHK(8)=1	CONTR140
	89 IF(IC.GE.2) GOTO 90	CONTR141
	GOTO 201	CONTR142
C		CONTR143
C	THIS SECTION OF CODING ORDERS THE DATA SO THAT NO OVERLAPPING OR	CONTR144
C	BACKTRACKING OCCURS DURING PLOTTING.	CONTR145
C		CONTR146
	90 IF(IC.GE.6) GOTO 300	CONTR147
	IF(KCHK(8).NE.1) GOTO 200	CONTR148
	DO 101 L=1,7	CONTR149
	IF(KCHK(L).NE.1) GOTO 101	CONTR150
	IC=IC+1	CONTR151
	PX(IC)=PX(1)	CONTR152
	PY(IC)=PY(1)	CONTR153
	IC=IC-1	CONTR154
	DO 102 M=1,IC	CONTR155
	PX(M)=PX(M+1)	CONTR156
	102 PY(M)=PY(M+1)	CONTR157
	IF((MOD(L,2).EQ.1).AND.KCHK(L).EQ.1) GOTO 200	CONTR158
	101 CONTINUE	CONTR159
C		CONTR160
C	PLOT DATA FOR THE USUAL CELL.	CONTR161
C		CONTR162
	200 CALL PLTCCD (1,0,PX(1),PY(1),IC,0)	CONTR163
	GOTO 201	CONTR164
C		CONTR165
C	THIS SECTION OF CODING DOES THE ORDERING AND PLOTTING IF 2 CONTOUR	CONTR166
C	LINE PASS THROUGH THE CELL	CONTR167
C		CONTR168
	300 IF(Z(I,J).GT.Z0.AND.Z(I+1,J+1).GT.0.0) GOTO 301	CONTR169
	IF(Z2.GT.Z0) GOTO 303	CONTR170
	302 N=IC+1	CONTR171
	PX(N)=PX(1)	CONTR172
	PY(N)=PY(1)	CONTR173
	CALL PLTCCD (1,0,PX(5),PY(5),3,0)	CONTR174
	CALL PLTCCD (1,0,PX(2),PY(2),3,0)	CONTR175
	GOTO 310	CONTR176
	303 CALL PLTCCD (1,0,PX(1),PY(1),3,0)	CONTR177
	CALL PLTCCD (1,0,PX(4),PY(4),3,0)	CONTR178
	GOTO 310	CONTR179
	301 IF(Z2.GT.Z0) GOTO 302	CONTR180

```

      GOTO 303
310 CONTINUE
C
C  CLEAR WORKING ARRAYS AND INITIALIZE FLAGS
C
201 IC=0
    DC 8 MN=1,8
    PX(MN)=0.
    PY(MN)=0.
    8 KCHK(MN)=0
100 CONTINUE
    1 CONTINUE
    2 CONTINUE
    RETURN
    END

```

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CONTR181
CONTR182
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